

**Written exam**

**First mane:**..... **Last mane :**.....

**Choose the correct answer:**

1) Let the random process defined by:  $X(t) = A \cos(\omega_0 t + \Theta)$ , where,  $A$  and  $\omega_0$  are constants,  $\Theta$  is a random variable with a probability density function:

$$f_{\Theta}(\theta) = \begin{cases} \frac{4}{\pi}, & |\theta| \leq \frac{\pi}{8} \\ 0, & \text{otherwise} \end{cases}$$

a) Its mathematical expectation is equal to:

- $\frac{4\sqrt{2}A}{\pi} \cos \omega_0 t$         $A$         $\frac{\sqrt{2}A}{\pi}$         $\frac{4\sqrt{2}A}{\pi}$

b) Its autocorrelation function equals:

- $\frac{A^2}{2} \cos \omega_0 \tau$         $\frac{A^2}{2} \cos \omega_0 \tau + \frac{2A^2}{\pi} \cos(2\omega_0 t + 2\omega_0 \tau)$   
  $A^2 \cos(2\omega_0 t + 2\omega_0 \tau)$         $\frac{2A^2}{\pi} \cos(2\omega_0 t + 2\omega_0 \tau)$

c) The random process  $X(t)$  is :

- Not stationary and not ergodic       Strict-Sense Stationary  
 Stationary and ergodic       Wide-Sense Stationary

2) Consider the hypothesis testing problem in which:

$$f_{Y|H_0}(y|H_0) = \text{rect}\left(y - \frac{1}{2}\right) \quad \text{and} \quad f_{Y|H_1}(y|H_1) = \frac{1}{2} \text{rect}\left(\frac{y-1}{2}\right)$$

a)  $\eta > 1/2$ , the decision regions are :

- For  $0 \leq y \leq 1 \Rightarrow$  decide  $H_1$  and for  $1 \leq y \leq 2 \Rightarrow$  decide  $H_0$   
 decide  $H_1$  or  $H_0$  in at the range  $0 \leq y \leq 1$  and decide  $H_1$  for  $1 < y \leq 2$ .  
 always decide  $H_1$   
 For  $0 \leq y \leq 1 \Rightarrow$  decide  $H_0$  and for  $1 \leq y \leq 2 \Rightarrow$  decide  $H_1$

b) The probability of false alarm is :

- $P_F = \int_{Z_1} f_{Y|H_0}(y|H_0) dy = \int_0^1 0 dy = 0$         $P_F = \int_{Z_1} f_{Y|H_0}(y|H_0) dy = \int_1^2 0 dy = 0$   
  $P_F = \int_{Z_1} f_{Y|H_0}(y|H_0) dy = \int_1^2 1 dy = 1$         $P_F = \int_{Z_1} f_{Y|H_0}(y|H_0) dy = \int_0^1 1 dy = 1$

3) Let  $X_1, \dots, X_n$  be independent and identically distributed random variables whose density is defined by:

$$f_{\theta}(x) = \begin{cases} \frac{x}{\theta} \exp\left(-\frac{x^2}{2\theta}\right) & \text{si } x > 0 \\ 0 & \text{Otherwise} \end{cases}$$

a) The MLE of  $\theta$  is given by:

$\hat{\theta}_{MLE} = \frac{1}{n} \sum_{i=1}^n x_i^2$       $\hat{\theta}_{MLE} = \frac{1}{n} \sum_{i=1}^n x_i$       $\hat{\theta}_{MLE} = \frac{1}{2n} \sum_{i=1}^n x_i^2$       $\hat{\theta}_{MLE} = \frac{1}{2n} \sum_{i=1}^n x_i$

b) The Cramer-Rao Bound is as follows :

$BCR = \frac{\theta^2}{n}$       $BCR = \frac{\theta}{2n}$       $BCR = \frac{\theta^2}{2n}$       $BCR = \frac{\theta}{n}$

4) The Doppler shift can be calculated using the expression:  $\delta f = f_e \frac{2v \cos \theta}{c}$  .

a) If  $f_e=25\text{GHz}$ ,  $c=3 \times 10^8\text{m/s}$ ,  $\theta=25^\circ$  and  $\delta f=3.3567\text{ KHz}$ , so:

$v=80\text{ Km/h}$       $v=20\text{ m/s}$       $v=25\text{m/s}$       $v=120\text{Km/h}$

b) If  $f_e=25\text{GHz}$ ,  $c=3 \times 10^8\text{m/s}$ ,  $v=100\text{Km/h}$  and  $\delta f=4.3504\text{ KHz}$ , so:

$\theta=30^\circ$       $\theta=15^\circ$       $\theta=20^\circ$       $\theta=25^\circ$

5) Using 3 distributed CA-CFAR detectors (identical case), the probability of false alarm, using exponential conditional probability laws and the “And” fusion rule is given by the following expression:

$$P_F = [1 + T]^{3N}$$

a) If  $N=32$  and  $P_F=10^{-4}$ , the constant multiplier  $T$  equals:

0.3335     0.7783     0.2115     0.1007

b) By considering these conditions and setting  $\mu=25\text{ dB}$ , the detection probability is equal to :

$P_D = \left[1 + \frac{T}{(1 + \mu)}\right]^{-3N} = 0.9685$       $P_D = \left[1 + \frac{T}{(1 + \mu)}\right]^{-3N} = 0.69$

$P_D = \left[1 + \frac{T}{(1 + \mu)}\right]^{-3N} = 0.97$       $P_D = \left[1 + \frac{T}{(1 + \mu)}\right]^{-N} = 0.9669$

*Good luck*